COST E55 – Zürich

Quantifying Ductility in Timber Structures

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Background and Motivation



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EN 1990: Basis of design, Basic requirements 2.1

- (1): Sustain all actions
- (2): Adequate resistance, serviceability and durability
- (3): Fire resistance
- (4): A structure shall be designed and executed in such a way that it will not be damaged by events such as:
 - explosion,
 - impact, and
 - the consequences of human errors,

to an extent disproportinate to the original case.

Basis of design

- EN 1991-7: Accidental actions
 - Impact from traffic
 - Internal explosions

- EN 1995-1-1:
 - Only strength (and serviceability)



Basis of design

- EN 1998: Earthquakes
 - Static ductility (3 cycles, 0.8^*F_u):
 - Ductility class:
 - Low (D< 4)
 - Medium (4<D<6)
 - High (D>6)
 - Take into account:

- Initial slip in connections
- E₀ values (+ 10%)

$$D = \frac{\mathcal{E}_u}{\mathcal{E}_0}$$

Single family housing or few stories



• Wooden structure housing damage at the 1995 Kobe earthquake (photo by Michio Miyano)

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20 storied building?

(Ramstad arkitekter)



TRE: Skissene viser et alternativ til bærende konstruksjoner som vurderes i mulighetsstudien. Først 25 bærende søyler, deretter bjelkelag, 400 x500 mm før 180 mm massivtredekker legges inn. Så kommer diagonale kryssavstiver og til isist glassfasaden med utkragende bokser i massivtre. FOTO. REIJLF RAMSTAD ARKITEKTER

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INTN



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Loading Conditions Testing Failure modes



Loading and Failure Modes:

- Static loading (Load is constant)
 - Snow on roof
 - (Slowly) Increased variable load
 - Decrease in resistance
- Dynamic loading (Load time dependent)
 - Impact e.g. from wild vehicles
 - Impact from falling mass above
 - Explosion
 - Earthquake
 - Sudden change in load distribution due to partly failure (e.g. due to human errors?)













Constitutive Modeling



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Total strain models:

• In general: $\sigma = f(\varepsilon)$

- Power law:
- Prager:
- Voce:

$$\sigma = C_1 + C_2 \varepsilon^n$$

$$\sigma = \sigma_0 \tanh(E\varepsilon/\sigma_0)$$

$$\sigma = C_3 + C_4 \left(1 - \exp(-C_5 \varepsilon)\right)$$

- Jorissen -Fragiacomo:
- Menegotto Pinto:

$$\sigma = \sigma_0 \left(1 - \exp\left(-\frac{K_1}{\sigma_0}\varepsilon\right) \right) + K_1 \varepsilon \left(1 - \exp\left(-\frac{K_1}{\sigma_0}\varepsilon\right) \right) \le \sigma_{\max}$$

$$\frac{\sigma}{\sigma_0} = C_8 \left(\frac{\varepsilon}{\varepsilon_0}\right) + \left(1 - C_8\right) \frac{\frac{\varepsilon}{\varepsilon_0}}{\left[1 + \left(\frac{\varepsilon}{\varepsilon_0}\right)^n\right]^{\frac{1}{n}}}$$

Constitutive piecewise models:

• Elastic - elastoplastic domain (piecewise - constant shift)

$$\sigma = \begin{cases} E\varepsilon & \text{for } 0 \le \varepsilon < \frac{\sigma_0}{E} = \varepsilon_0 \\ \sigma_0 + f(\varepsilon - \varepsilon_0) & \text{for } \varepsilon \ge \varepsilon_0 \end{cases}$$

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• Elastic or plastic domain (decoupled)

$$\sigma = \begin{cases} E \cdot \varepsilon & \varepsilon < \sigma_0 / E \\ f(\varepsilon_p) & \varepsilon \ge \sigma_0 / E \end{cases}$$





• Maximum (ultimate) strain:

$$\frac{d\sigma}{d\varepsilon_p} = \frac{f(\varepsilon_p)}{d\varepsilon_p} = 0 \quad \to \varepsilon_{pua}$$

$$\varepsilon_{pu} = \min \begin{cases} \varepsilon_{p\max} \\ \varepsilon_{pua} \end{cases}$$



Fracture (softening branch)

Total internal energy

$$W_t = W_e + W_p$$

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Example 1: Moment vs. rotation





• Initial stiffness and slip (by regression) :

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E = 70643 kNm/rad $\varepsilon_i (= \phi_i) = \frac{33.787}{70643} = 0.000478$ rad

• Linear elastic model: zero stress for zero strain

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"Plastic" model

• Remove slip and elastic deformation

$$\varepsilon_p = \varepsilon - \varepsilon_i - \frac{\sigma}{E}$$

• Fit analytical expression (polynom?)

$$\sigma = f(\varepsilon_p)$$

$$\sigma = \sigma_0 + A\varepsilon_p + B\varepsilon_p^2 + C\varepsilon_p^3$$

• Results:

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 $\sigma_{0} (= M_{0}) = 72.663 \text{ kNm} \qquad \varepsilon_{pu} = \min \begin{cases} \varepsilon_{p \max} = (0.00067) \\ \varepsilon_{pua} = 0.00036 \end{cases}$ $B = -9.19 \cdot 10^{7} \text{ kNm/rad}^{2}$ $C = 2.78 \cdot 10^{9} \text{ kNm/rad}^{3} \qquad \varepsilon_{pf} = \min \begin{cases} \varepsilon_{p \max} = 0.00067 \\ \varepsilon_{p \max} = 0.00067 \\ \varepsilon_{p fa} = (0.00078) \end{cases}$

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Example 2: Single dowel test



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"Plastic" model

• Remove slip and elastic deformation

$$\varepsilon_p = \varepsilon - \varepsilon_i - \frac{\sigma}{E}$$

• Fit analytical expression (2 terms Voce)

$$\sigma = f(\varepsilon_p)$$

$$\sigma = \sigma_0 + Q_1 \left(1 - e^{-C_1 \varepsilon_p} \right) + Q_2 \left(1 - e^{-C_2 \varepsilon_p} \right)$$

Results

$$\sigma_{0} = 12.14 \text{ kN}$$

$$Q_{1} = 8.01 \text{ kN}$$

$$\varepsilon_{pu} = \min \begin{cases} \varepsilon_{p \max} = (4.87) \\ \varepsilon_{pua} = 0.49 \end{cases}$$

$$C_{1} = 8.55 \text{ mm}^{-1}$$

$$Q_{2} = -3.10 \text{ kN}$$

$$\varepsilon_{pf} = \min \begin{cases} \varepsilon_{p \max} = 0.00067 \\ \varepsilon_{pfa} = (N.A.) \end{cases}$$

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Ductility quantification



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Ductility measures: $u_y = u_0 \rightarrow \varepsilon_0$



Strain based ductility measures "Ds"

$$Ds_{tu0} = rac{\mathcal{E}_u}{\mathcal{E}_0} = rac{\mathcal{E}_u}{\sigma_0/E}$$

$$Ds_{pu0} = \frac{\varepsilon_{pu}}{\varepsilon_0} = \frac{\varepsilon_{pu}}{\sigma_0/E}$$
$$Ds_{pf0} = \frac{\varepsilon_{pf}}{\sigma_0/E}$$

$$Ds_{tu} = \frac{\varepsilon_{pu}}{\varepsilon_{u}} = \frac{\varepsilon_{pu}}{\sigma_{u}/E + \varepsilon_{pu}}$$
$$Ds_{tf} = \frac{\varepsilon_{pf}}{\varepsilon_{f}} = \frac{\varepsilon_{pf}}{\sigma_{f}/E + \varepsilon_{pf}}$$

$$Ds_{ue} = \frac{\varepsilon_{pu}}{\varepsilon_{eu}} = \frac{\varepsilon_{pu}}{\sigma_u/E}$$

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 $\varepsilon_{u} = \frac{\sigma_{u}}{F} \left(1 + Ds_{ue} \right)$

•
$$\mathcal{E}_u = \mathcal{E}_0$$
 Brittle material has ductility = 1 !!
(EN 1998)

• The offset from linearity is far from unique Scaling by "yield point" should be avoided

 Scaling by max. strain give 0 < D < 1, but insufficient distinctions between responses

- Scaling by elastic strain at ultimate force: OK. Static ductility up to ultimate force level.
- Easy strain calculation.

Energy based ductility measures "Dw"

$$Dw_{ue} = \frac{W_{pu}}{W_{eu}} = \frac{\int_{0}^{\varepsilon_{pu}} \sigma d\varepsilon_{p}}{\int_{0}^{\sigma_{u}} \sigma d\varepsilon_{e}} = \frac{\int_{0}^{\varepsilon_{pu}} f(\varepsilon_{p}) d\varepsilon_{p}}{\frac{\sigma_{u}^{2}}{2E}}$$

• For static loading (up to ultimate load) Plastic energy dissipation/elastic energy

$$Dw_{fe} = \frac{W_{pf}}{W_{eu}} = \frac{\int_{0}^{\varepsilon_{pf}} \sigma d\varepsilon_{p}}{\int_{0}^{\sigma_{u}} \sigma d\varepsilon_{e}} = \frac{\int_{0}^{\varepsilon_{pf}} f(\varepsilon_{p}) d\varepsilon_{p}}{\frac{\sigma_{u}^{2}}{2E}}$$

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• Dynamic loading (up to fracture) Plastic dissipation/max elastic energy

 $W_{tu} = \frac{\sigma_u^2}{2E} \left(1 + D w_{ue} \right)$

$$W_{tf} = \frac{\sigma_u^2}{2E} \left(\left(\frac{\sigma_f}{\sigma_u} \right)^2 + Dw_{fe} \right)$$

• Total energies



2 examples:



Final Remarks (Quantifying):

• Decomposition of strains:

$$\varepsilon = \varepsilon_e + \varepsilon_p \qquad \varepsilon_e = \sigma/E$$

• Decoupled models:

$$\sigma = \begin{cases} E \cdot \varepsilon & \varepsilon < \sigma_0 / E \\ f(\varepsilon_p) & \varepsilon \ge \sigma_0 / E \end{cases}$$

- Quantifying measured test response by regression on to analytical models
 - Initial slip
 - Elastic linear response
 - "Plastic" nonlinear response
- Determine parameters of the analytical models
- Compute derived properties from the analytical models



Final Remarks: Ductility



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